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# Aerospike's Strong Consistency Mode of Operation

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# Aerospike's Strong Consistency (SC) Mode

## Outline

- What does it get me?
- How does it work?
- Is there a performance hit?
- How do I configure it?



# Strong Consistency Mode – What does it get me?

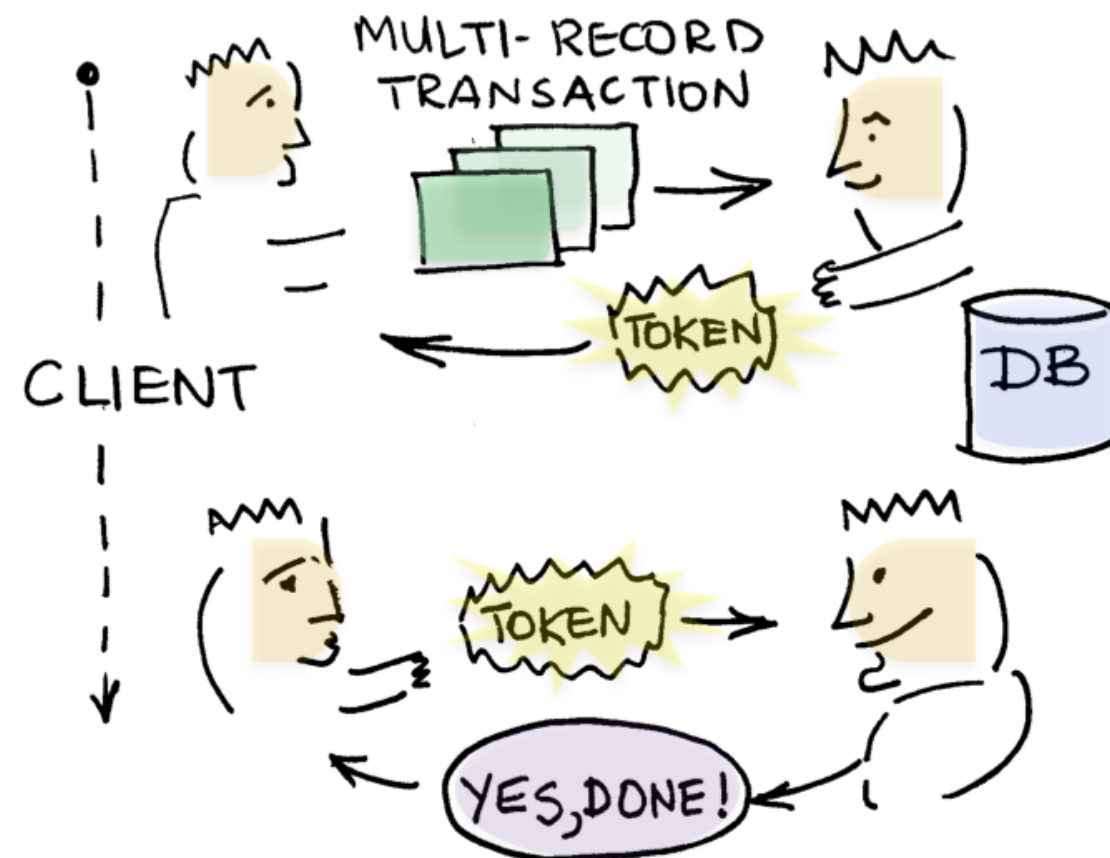
# Why Strong Consistency?

**Premise:** I am going to use [Aerospike as a System of Record](#) then normal operations OR during any database failure modes, [there should be:](#)

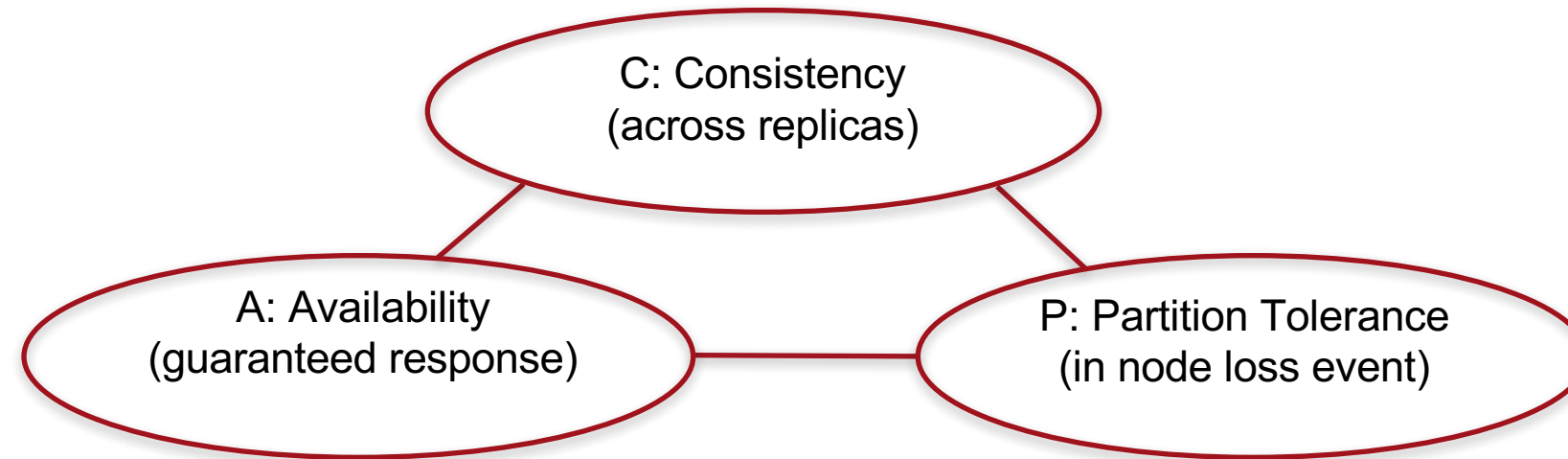
- [No Stale Reads](#)
  - Reading data that is not the most recently committed value.
- [No Dirty Reads](#)
  - Reading data that is not yet committed.
- [No Data Loss](#)
  - Losing data that was committed.

# How Relational Databases Address Strong Consistency

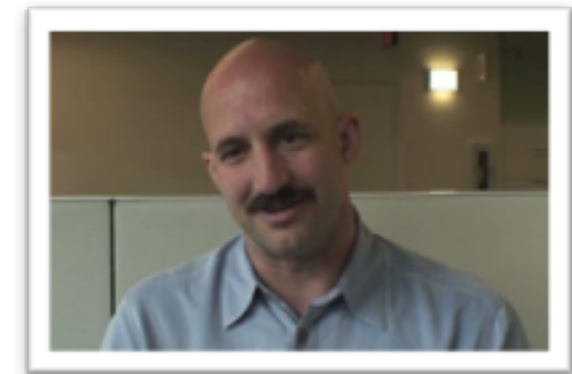
- If on single node storage, obviates need for dealing with partition tolerance.
  - Single copy of data.
- **Two Phase Commit.**
  - Allows rollbacks and multi-record transactions but is **slow, very hard to scale up.**



# CAP Theorem for Distributed Databases



- You can only design to guarantee two of the three.
- **CA** – High consistency and availability, *nodes never go down*. (Not a realistic scenario!)
- **Practical Definition:** In case of a node loss, choose between C or A in your distributed database design.
- **AP** – High availability on a cluster of nodes, accept Inconsistency or Eventual Consistency.
- **CP** – **Strong consistency** and cluster scalability, accept some unavailability during node failure/addition.



Professor Eric Brewer, UC Berkeley, explains the CAP theorem

# Strong Consistency Challenge with Distributed DBs

- Distributed databases replicate data to prevent data loss on node failure.
- 3 Copy Consensus based designs with flaky clients can result in:
  - Dirty Reads (client writes to one node only and crashes).
  - Blocked Reads – no consensus (client updates/crashes - different nodes with different values).
  - Blocked Updates (update requiring a read, and, reads are blocked due to consensus failure).
- Distributed Master AP designs can suffer data inconsistency:
  - Under "Split Brain" situations.
  - Clock skew, outages, merges can lead to written data lost even after a read.

# Split Brain – It Happens!

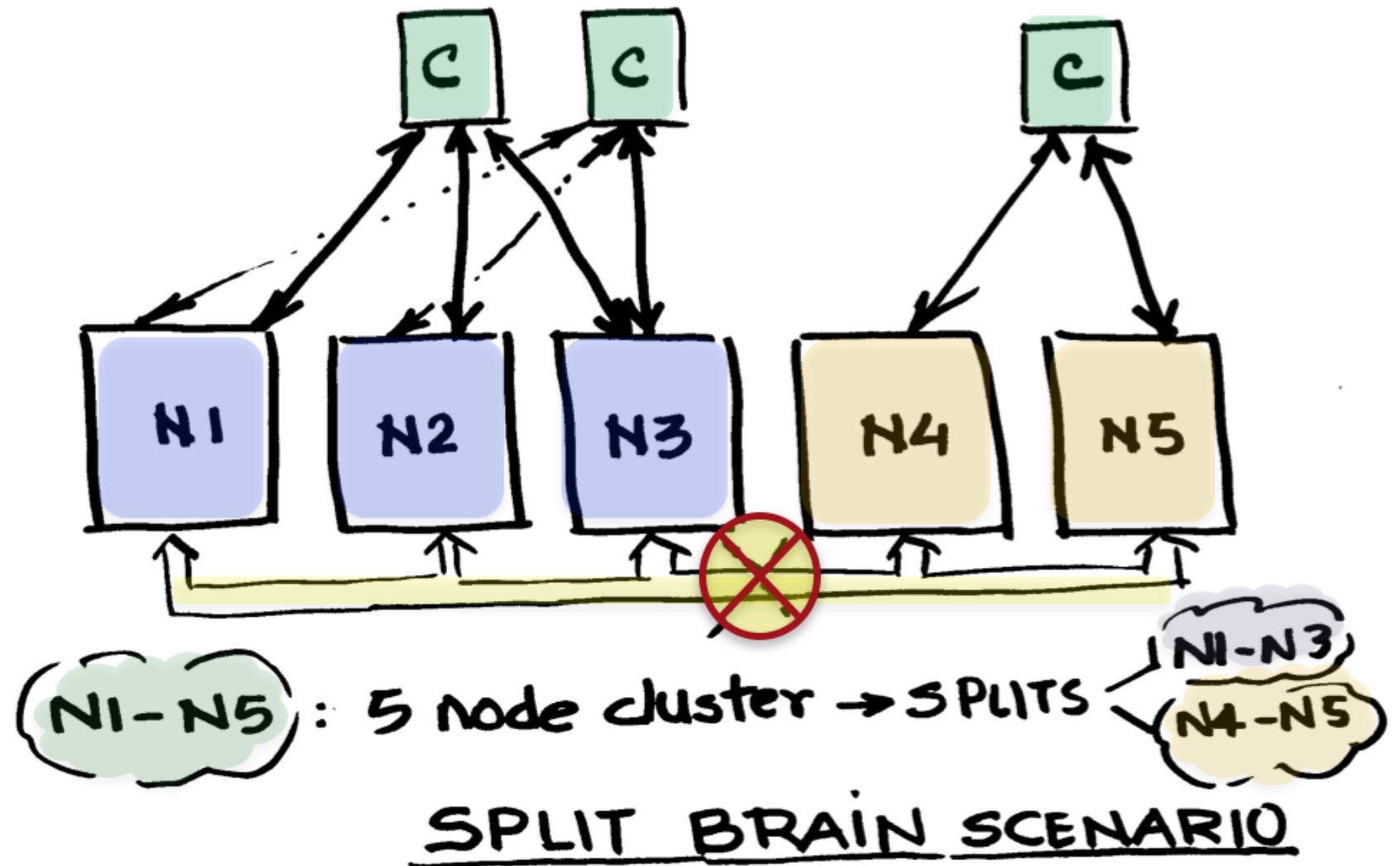
- Split Brain for the purposes of our discussion is defined as a scenario where a cluster splits into two or more separate clusters, each thinking it is **the** cluster.

In AP mode, we get:

- Availability* at the expense of *Consistency*.

In SC mode, we are rigorous about:

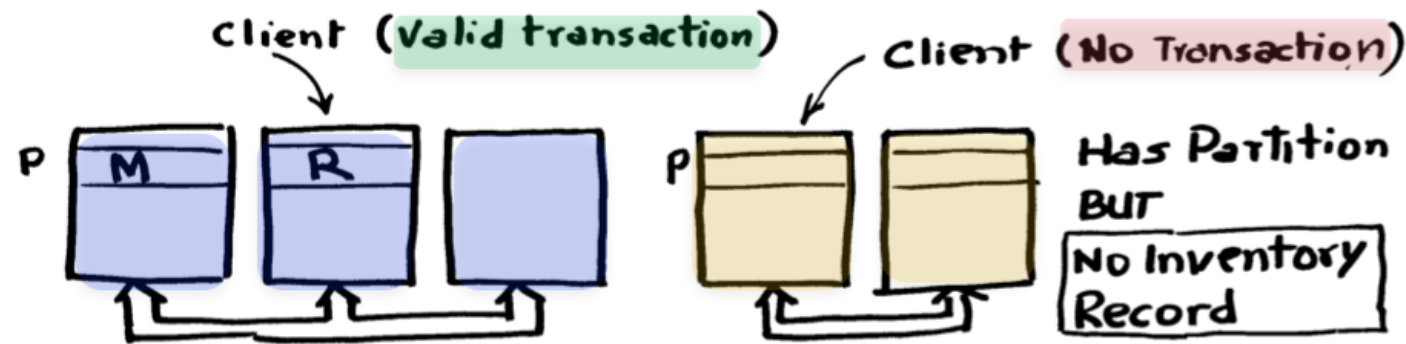
- On the fly cluster changes – nodes going in or out of the cluster.



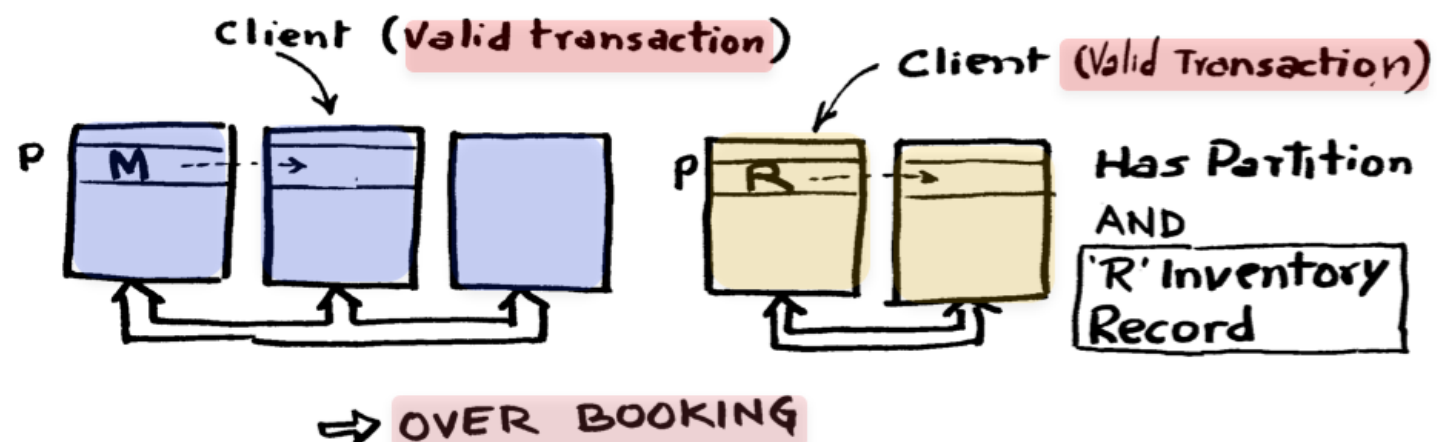


# Split Brain AP Case – Inventory Transaction Example

- Case 1: Master & Replica on same split, other split will not have inventory record → **Inventory data not found on read but can be added (written).**



- Case 2: Master & Replica on split clusters lead to data duplication and create valid over-bookings → **Inconsistency.**



# Aerospike's Strong Consistency Mode for Single Record Transactions

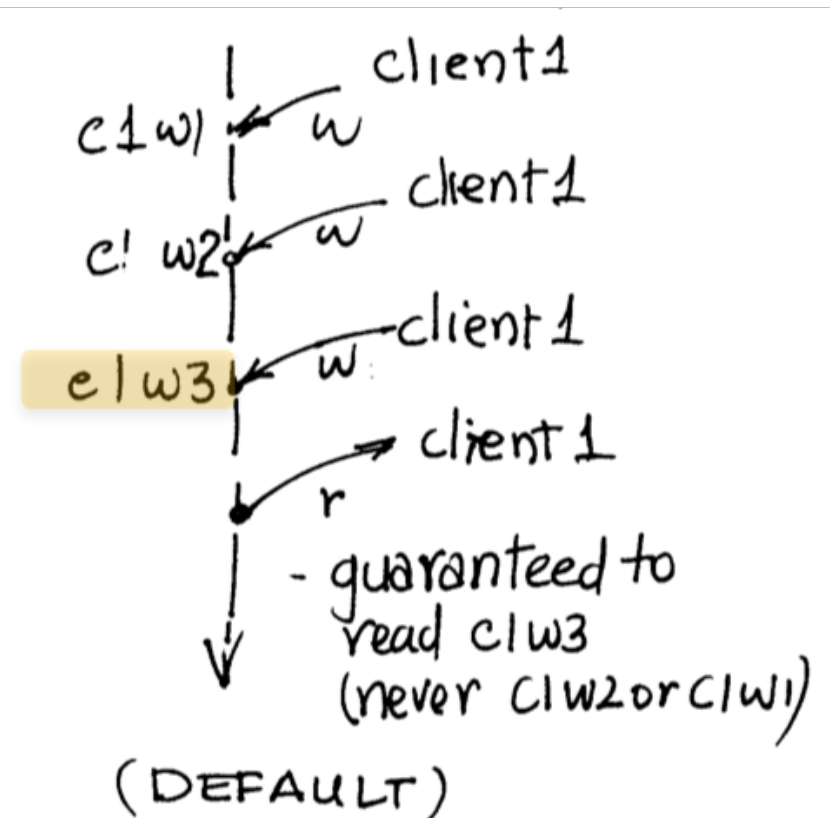
- Configured on a namespace basis.
- Cluster membership is identified as a "roster" of nodes.
- Strong Consistency Mode guarantees:
  - Successful writes or updates are never lost.
  - No Dirty Reads.
  - Client can do 'Linearizable' Reads on a per read basis.
    - With 'linearizable', all clients see the same sequence of updates.
  - Immediate Consistency.
  - Guaranteed to handle up to 27 seconds clock skew between nodes.
    - Implies client never has to merge data or deal with conflicts.
- Aerospike's Strong Consistency Mode passes Jepsen Tests!

# Read Linearizability in Strong Consistency Mode

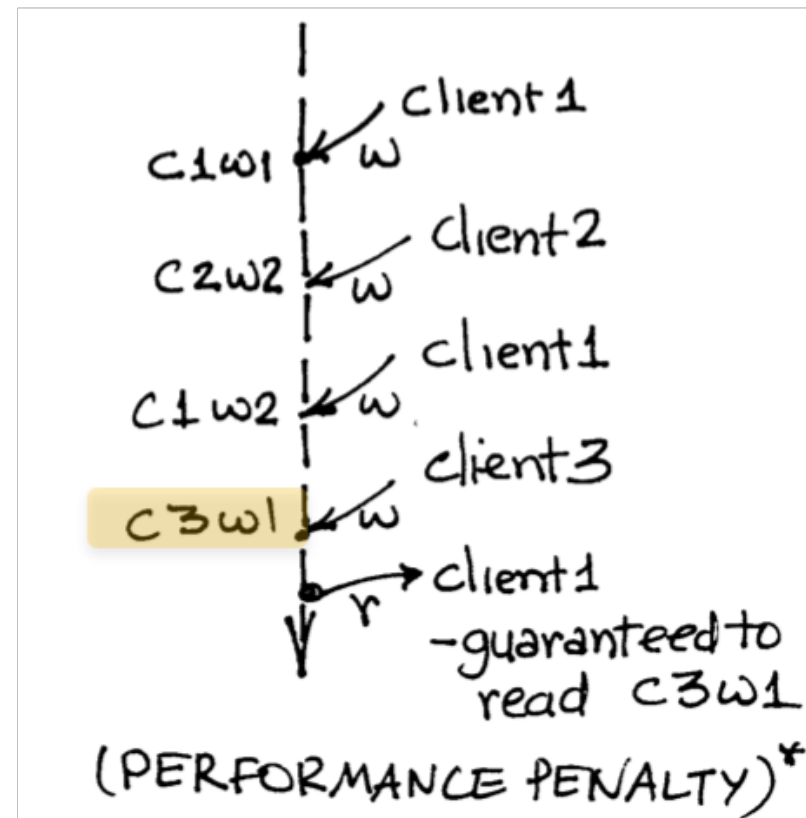
In SC Mode, reads can be configured to never return "stale" reads.

- **Session** Consistency is the **default**.
- Global Read Linearizability can be enforced on a per read transaction basis.

## Session Consistency

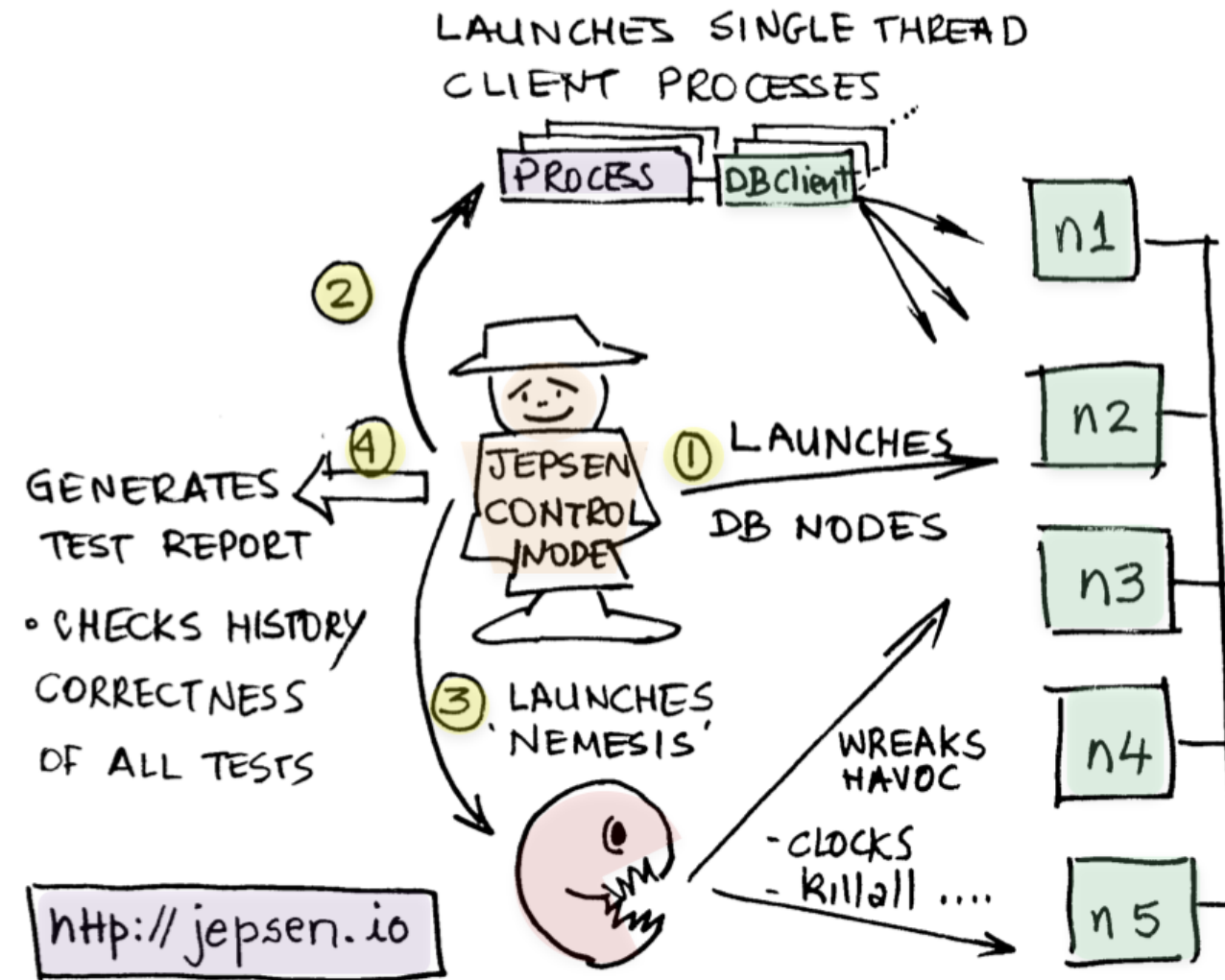


## Global Linearizability



# What are Jepsen Tests?

- Conducted by <http://jepsen.io> to find consistency holes in distributed databases.



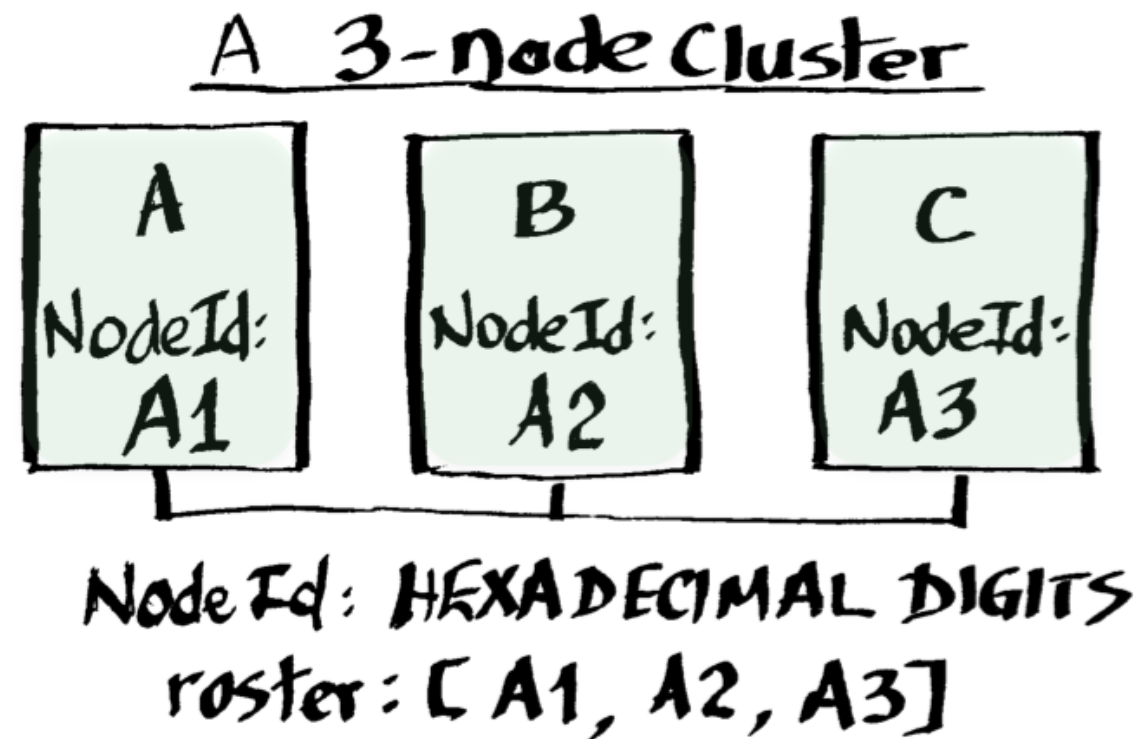


# Strong Consistency Mode – How does it work?

# Definition of Terms: Cluster vs Roster

Mesh or Multicast – nodes find each other and form a **cluster**.

- Nodes have **Node-IDs**.
- **Roster**: A set of nodes that define a SC Mode namespace.
- Nodes added subsequently to the cluster will not automatically extend an SC namespace without operator intervention. (Must update roster and "**recluster:**")



# Identifying a Roster

Configure on each node:

```
service {  
node-id A1 (must use 0-9, A-F only. i.e. Base 16 digits. )  
...  
}  
  
namespace ns1 {  
replication-factor 2  
strong-consistency true  
default-ttl 0  
  
...  
}
```

# Identifying a Roster

Identify the roster for namespace ns1:

```
$ asadm
```

```
Admin> asinfo -v "roster:namespace=ns1"
```

```
Admin> asinfo -v "roster-set:namespace=ns1;nodes=A1,A2,A3"
```

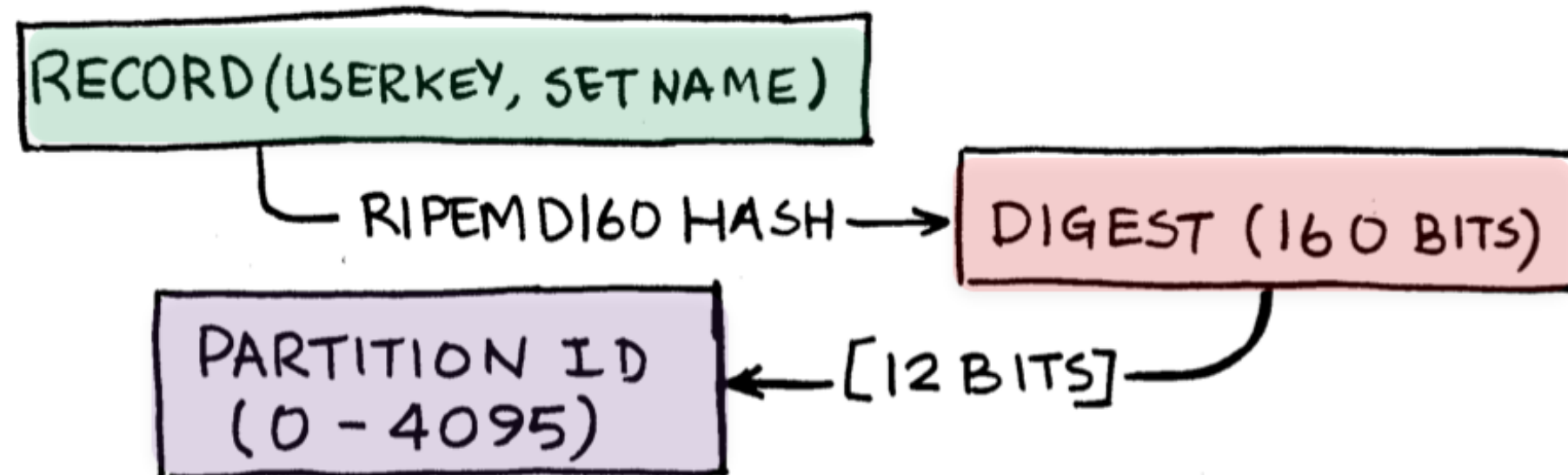
Elevate a pending\_roster to roster:

```
Admin> asinfo -v "recluster:namespace=ns1"
```



# Recap: Record Distribution and Partitions

- Set name + key type(1byte) + User key is hashed into a 20 byte value (40 Hexadecimal digits) using the RIPEMD160 hash function.
- This hash + additional data (fixed 64 bytes) are stored in Primary Index in RAM.
- 12 bits of this hash are used to compute the partition id.  $2^{12}=4096$ .



# Recap: Record Distribution and Partition Map

- 4096 partitions per namespace. Each namespace has its own Partition Map.
- Partition Map maps Partition id to Node id based on cluster membership.
- Partition map generated when cluster forms or changes.
- A namespace, set name & user key locate a record to a partition on a node.
- In SC Mode, a Partition 'Q' may be:
  - ACTIVE, UNAVAILABLE or DEAD.

**PARTITION TABLE**

PARTM ID	R1	R2	R3	R4	R5
0	B	D	E	A	C
1	E	C	A	D	B
⋮	⋮	⋮	⋮	⋮	⋮
4094	C	B	A	E	D
4095	D	E	A	B	C

MASTER REPLICAS  
PARTITION MAP (RF=2)

# SC Mode Terms: Roster-Master, Roster-Replica, Master, Replica

With all nodes defined in the roster up and running, we have:

**Roster Master** ( $r_m$ ) Designated master node for a partition in the roster.

**Roster Replica** ( $r_r$ ) Designated replica node(s) for a partition in the roster.

- One (RF=2) or more (RF>2) nodes that are identified as the Replicas for a Partition.
- $r_m$  and  $r_r$  designations do not change, even if node goes down, until the operator changes the roster & "reclusters". **(Different from AP mode where cluster changes are dynamic.)**

**Master** ( $m$ ) A Node **currently the working Master** for a Partition.

e.g.: A "full" Roster Replica that got promoted to Master on a cluster split.

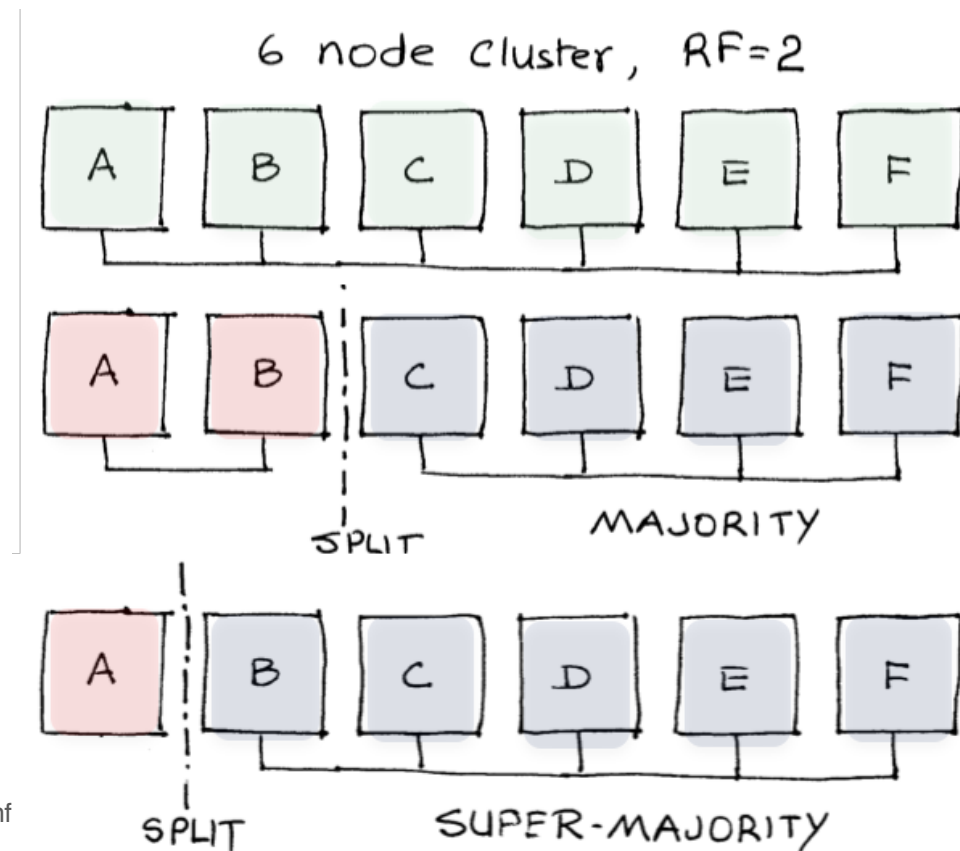
**Replica** ( $r$ ) A node **currently the working Replica** for a Partition.

e.g.: A node that got designated Replica due to a cluster split (receives copy of partition from Roster-Master or current Master on rebalance).

# SC Mode Terms: Strict Majority vs Super-majority

If a cluster splits into sub-clusters:

- **Strict Majority sub-cluster:** Number of nodes in sub-cluster  $> (\text{Roster Size} / 2)$ .
- **Super-Majority sub-cluster:** Less than "RF # of nodes" are down or split.
  - #nodes present should be  $> \text{RF}$
  - A super-majority sub-cluster has the full data, all partitions.
  - So, if  $\text{RF} > 1$ , under Rolling upgrade we will always have a super-majority sub-cluster.



# Partition State: Full Partition vs Subset Partition

A node is said to have a:

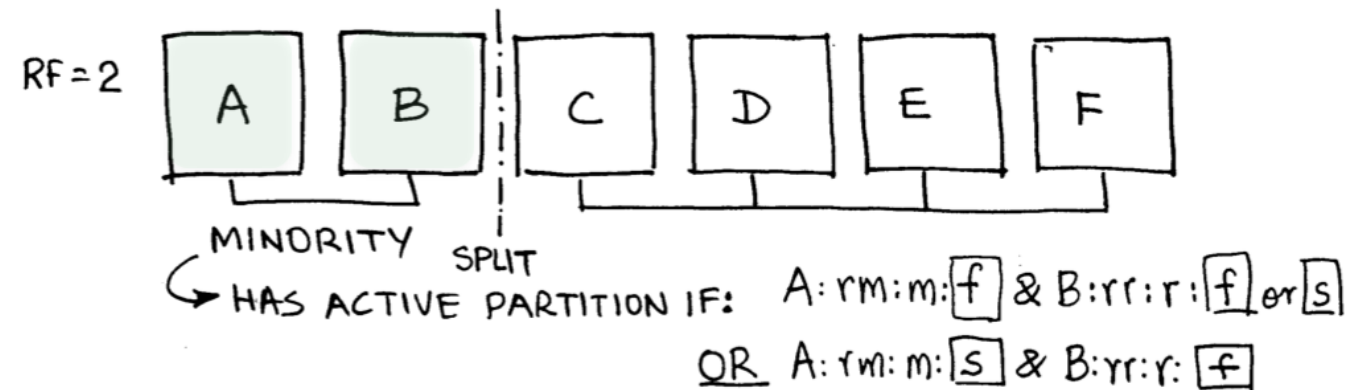
- **Full Partition:** (  $f$  ) It has a full copy of the data for that partition (prior to a split, normal operating cluster, fully rebalanced).
- **Subset Partition:** (  $s$  ) Node may be either a master or replica of a partition *but only has a subset of the data*. Needs to receive the rest of the data from rebalance in progress or needs to update its data from Duplicate Resolution (situation discussed later), in progress.
- Rule: A **node** that **leaves** the cluster (even if it was at "full" status), always **rejoins** the cluster with "subset" status. After rebalancing is complete, it can regain "full" status for that partition.

Next, Partition Availability: a) ACTIVE, b) UNAVAILABLE and c) DEAD.

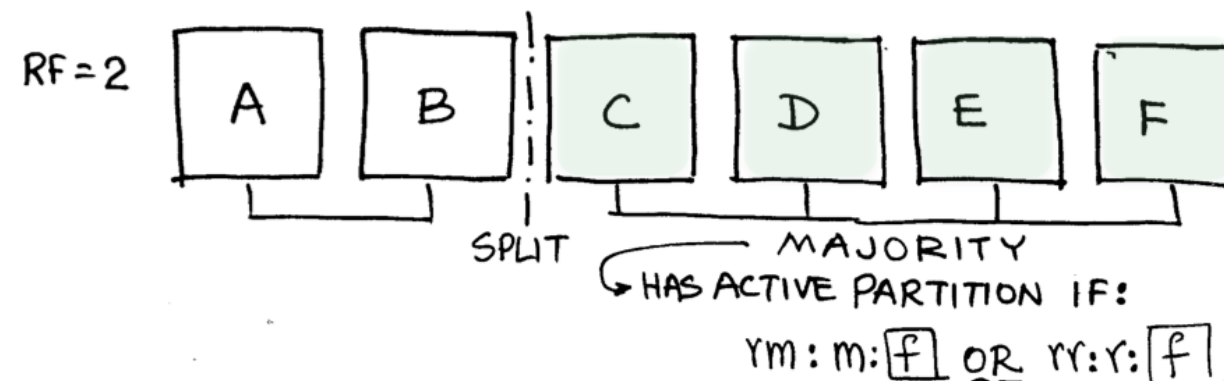
# Active Partition in Sub-Cluster: Rules

Partition in a Sub-Cluster is considered **Active for reads and writes** if:

- Sub-Cluster (regardless of size) has all Roster-master & Roster-replica(s) and at least one is "full". (Rule 1)

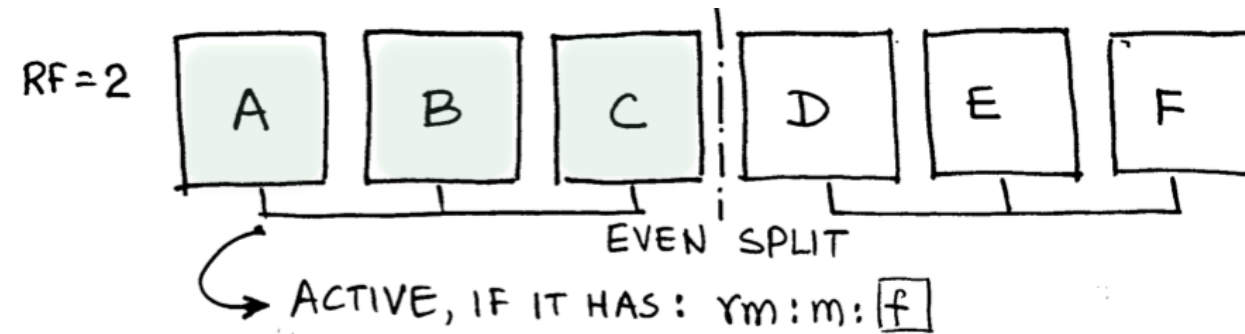


- OR** Sub-Cluster has a strict majority of nodes & at least one "full" of Roster-master or Roster-replica(s). (Rule 2a)

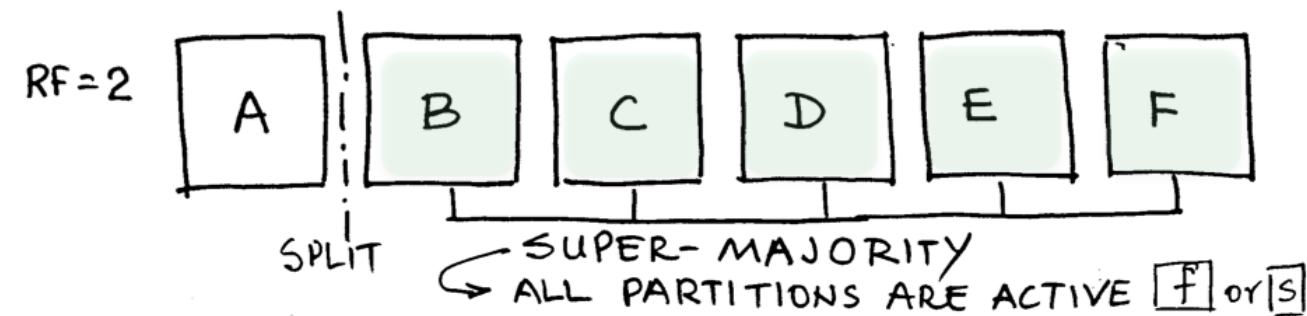


# Active Partition in Sub-Cluster: Rules (cont.)

- **OR** If cluster splits evenly (not a strict majority) into two sub-clusters, the sub-cluster holding the Roster-master *and* it must be "full" has the active partition. (Rule 2b)



- **OR** Super-Majority Cluster – "full" or "subset" – all partitions are active.
  - Rolling Upgrade is Super-Majority. (Rule 3)

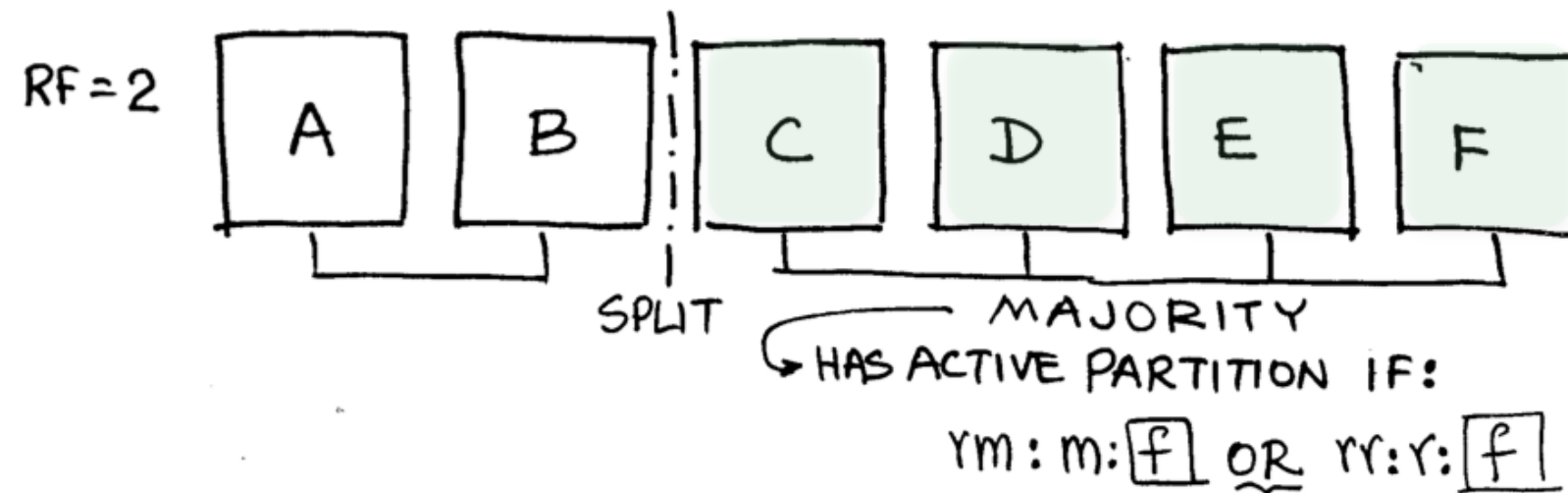


- There can be only one sub-cluster that has the partition master at any given time.
- Reads and Writes succeed only if the sub-cluster has at least RF number of nodes.

# "Unavailable" Partitions

A Partition is considered "Unavailable" in a Sub-Cluster if:

- It is not Active in that Sub-Cluster
  - For e.g., if C-D-E-F have  $rm:m:f$  of Partition Q, then Q is unavailable in A-B



- If greater than or equal to "RF # of nodes" go out, with persistent storage, some partitions will become unavailable till those nodes rejoin the cluster. With data-in-memory only, you will lose the partition data. → **In SC Mode, using in-memory only namespaces is not recommended.**



# "Dead" Partitions

A Partition is considered "Dead" if the partition is not available with full roster of nodes up:

- Some or all of underlying record **storage is detected as lost while all nodes are still running and connected**. This can happen if:
  - In storage-engine-memory, node(s) restarted under certain conditions. e.g.:: restart  $\geq$  RF # of nodes simultaneously.
  - One or more SSD drives storing the data, fail or are erased under certain states of the cluster.

→ **Once a partition is dead, cluster must be revived** (operator intervention).

```
Admin> asinfo -v "revive:namespace=ns1"
```

```
Admin> asinfo -v "recluster:"
```

**Note:** When you revive a dead partition, you may or may not have lost data.



# Transactions in SC Mode

# Writes in SC Mode

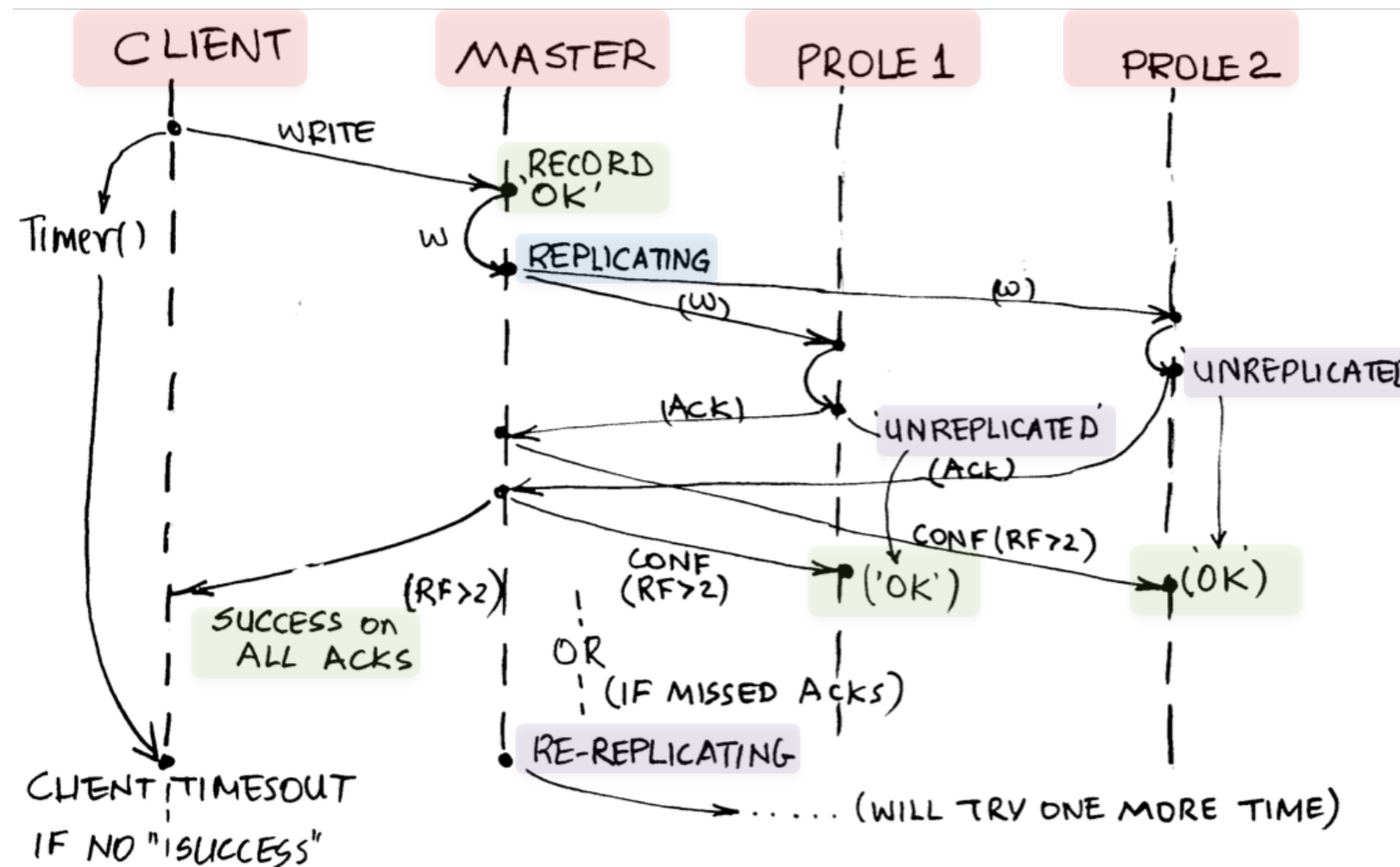
**SC Mode Promise:** Writes reported as "succeeded" to client are never lost by the server.

- Only one sub-cluster will take writes – single master for a partition.
- Writes must be acknowledged by all replicas before master acks to client.
- Master acks back to replicas also if  $RF > 2$ . (Redundant for  $RF = 2$ ).
  - Huge savings on future Duplicate Resolution, if needed.

# Record State in SC Mode

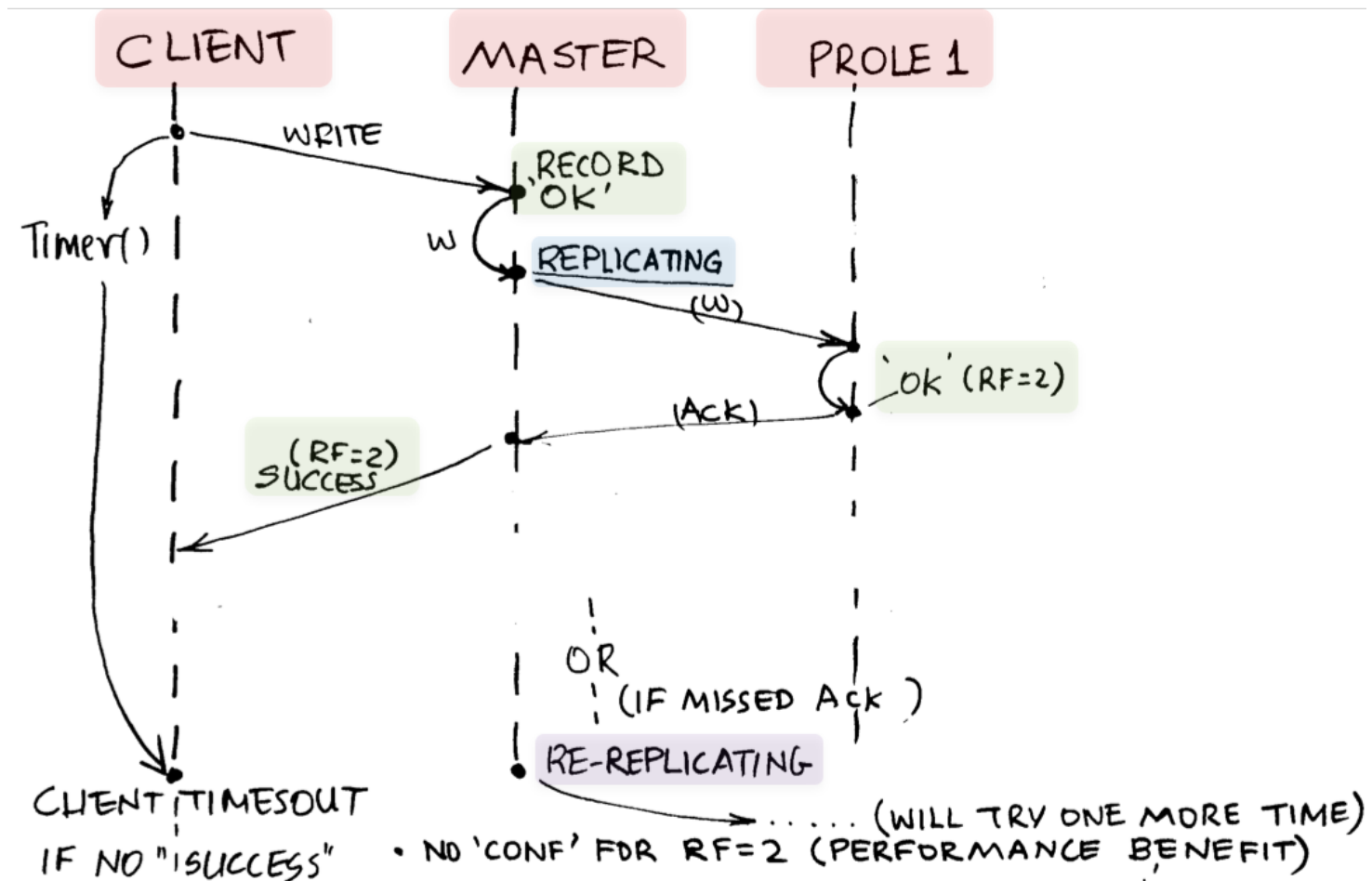
- **2 bits in Primary Index** store 4 possible states of a record.
  - **OK** (normal state, *replicated* to RF number of nodes).
  - **Replicating** (State on Master, in the process of writing to Proles).
  - **Re-Replicating** (State on Master, if Acks not received from all Proles).
  - **Un-Replicated** (State on Master if Replication fails, on Prole if  $RF > 2$  and Confirmation not received).
- 
- Let's look at a write transaction for: a)  $RF > 2$  vs b)  $RF = 2$ .
  - Here, starting state of record on Master is 'OK'.

# Write Transaction in SC Mode (RF>2)



- Client TIMEOUT if SUCCESS not received from server.
- Client's view on TIMEOUT of Record status on server – UNKNOWN. Could be on Master or not, OR on Master and Prole1, OR on Master and All Proles...

# Write Transaction in SC Mode (RF=2)



- Client TIMEOUT if SUCCESS not received from server.
- Client's view on TIMEOUT of Record status on server – UNKNOWN. Could be on Master or not, OR on Master and Prole...
- Note: No "CONF" messages required for RF=2 (Performance Benefit – fewer fabric msg passing.)

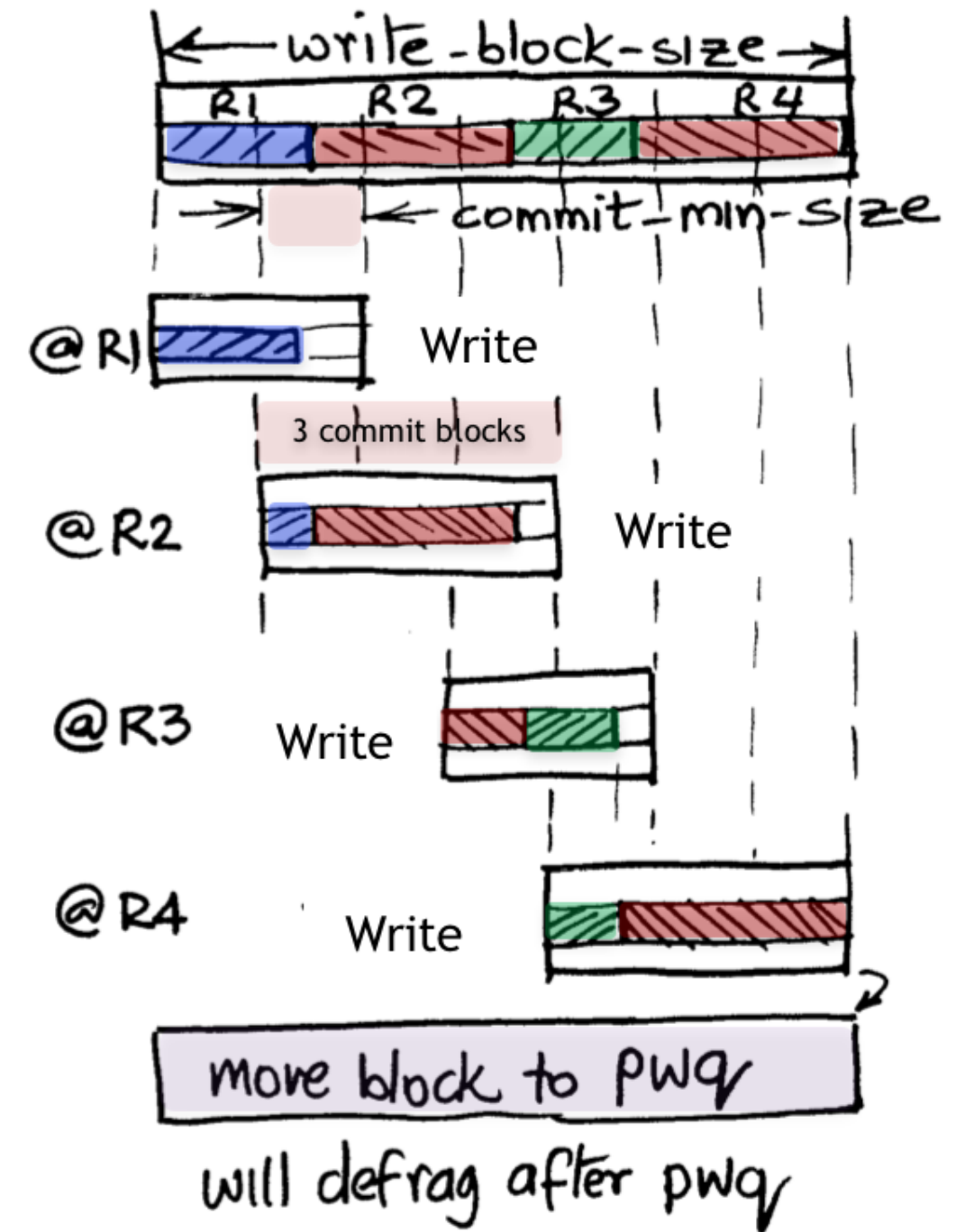
# Durability in SC Mode

## Durability in Strong Consistency Mode

**commit-to-device: true** Flush to disk before ack to client. (optional)

**commit-min-size: (default selected by Aerospike)**  
Set to a power of 2.

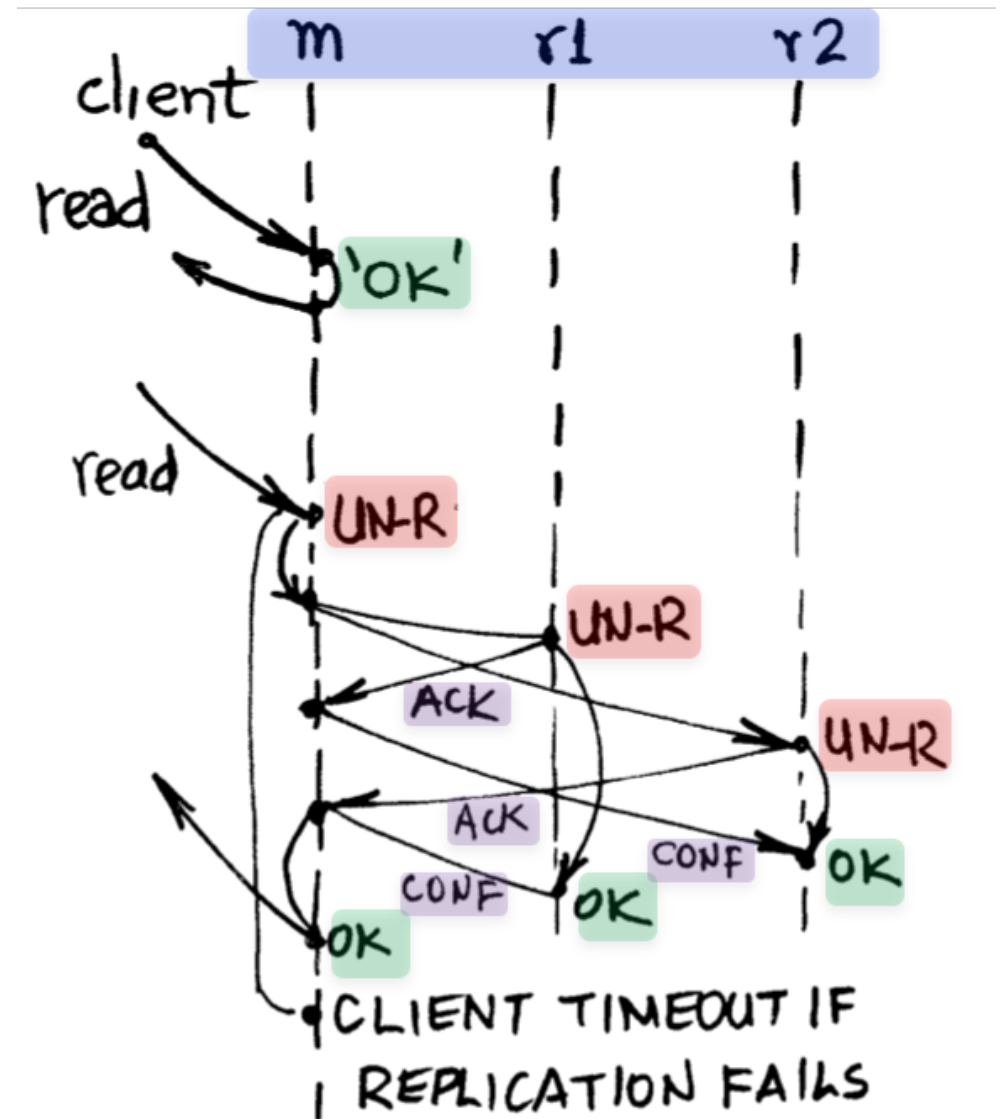
- Only applicable if **commit-to-device** is true.
- Records are written to persistent storage on every write at **commit-min-size** boundaries.
- **Commit-to-device** ensures that **no successful write is ever lost** even if master and replica both go down simultaneously (within *flush-max-ms* worst case) before the write-block-buffer has flushed to device.



# No Dirty Reads in SC Mode

What are Dirty Reads? Reading data that is not yet committed.

- Reads go to Partition Master
- Normal Cluster, steady state.
  - **Case 1:** Record state = "OK" on master, master returns record to client.
  - **Case 2:** Record state = "UNREPLICATED", master will re-try replication first. If success, return record to client or client will TIMEOUT.

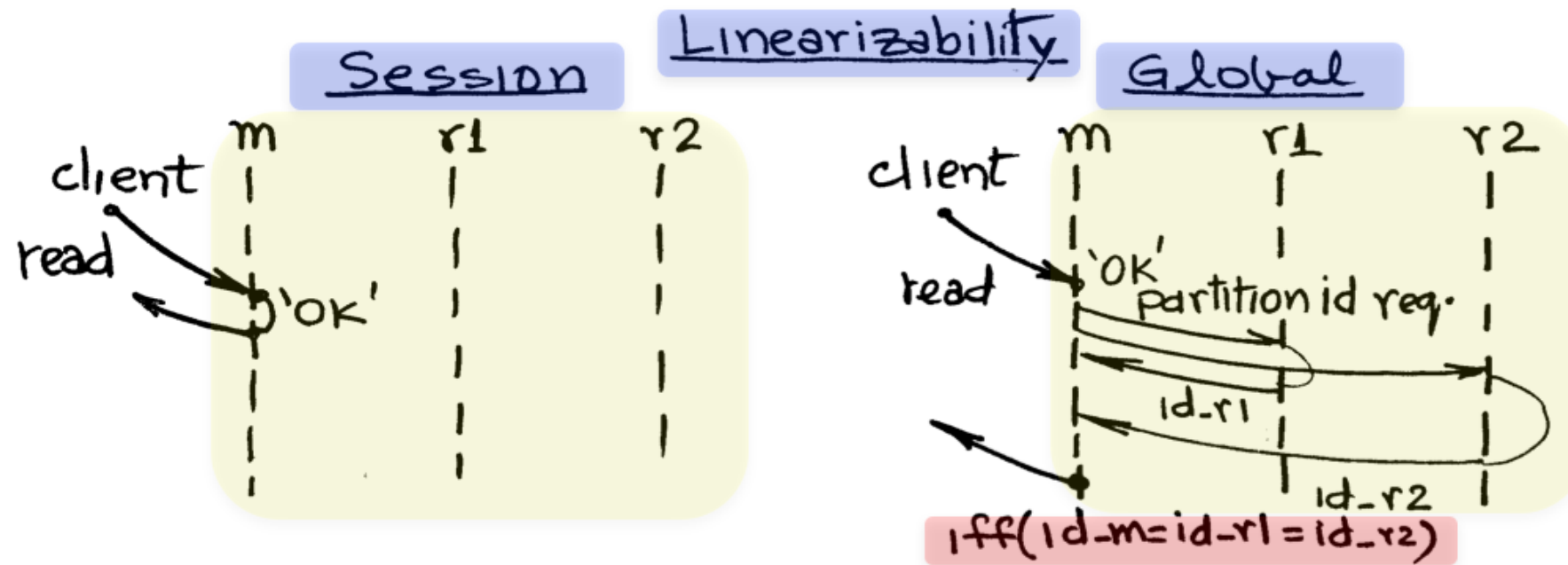




# Global Linearized Reads in SC Mode

## Global Linearized Read Mode

- **No stale reads**, requires extra network round-trip (master requests 32 bit partition regime from each replica and compares with its regime value).



## In what situation can replica partitions differ from master?

- Split brain heals where all but the master node formed a new cluster but the master node had not observed the split.



# Relaxed Reads in Strong Consistency Mode - Ver 4.5.2.1+.

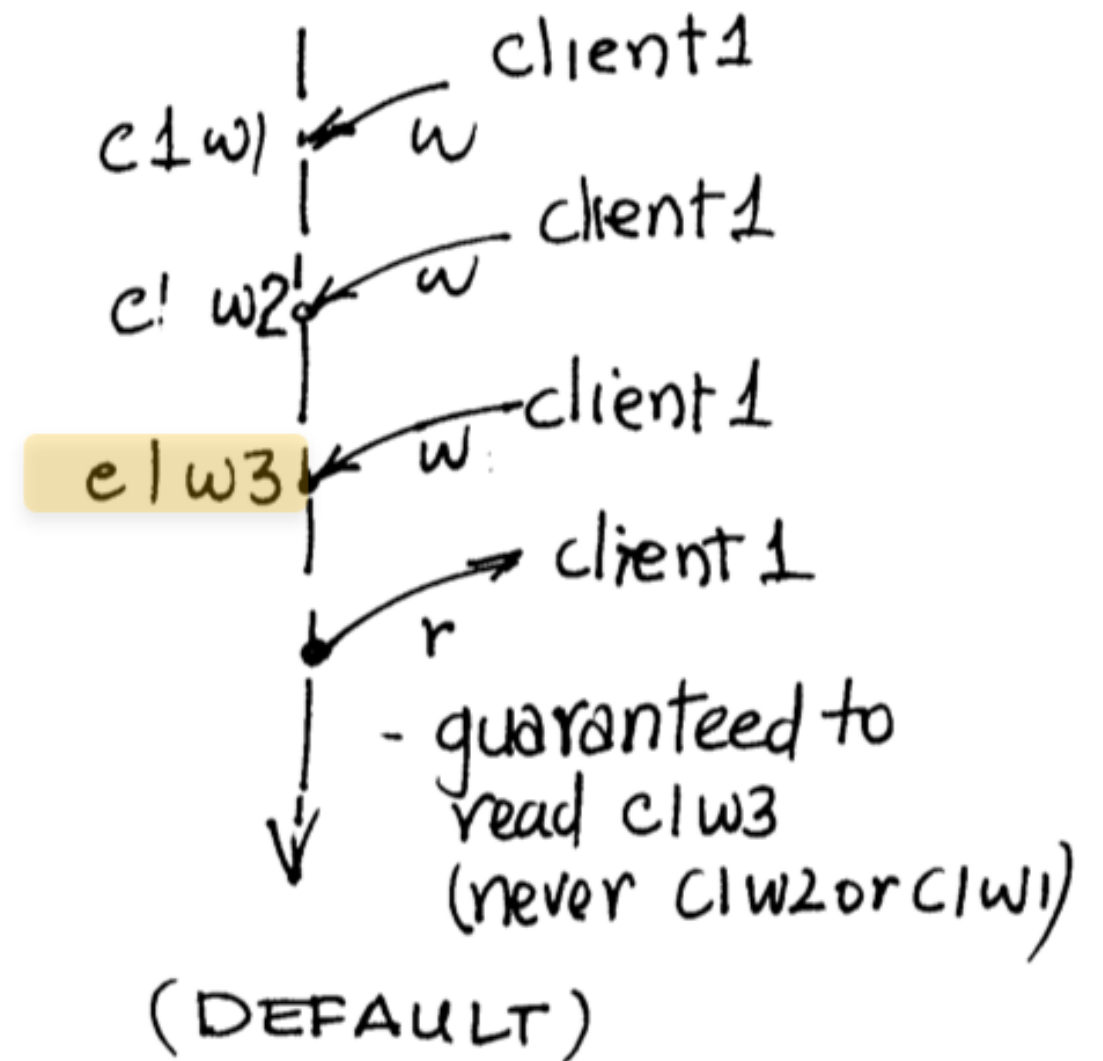
# Need For Relaxed Consistency Reads

- Recall, in SC Mode, default session consistent reads always read from Partition Master.
- 1) Customers using SC Mode with Rack Awareness, 2 racks in separate AZs:  
**Client should be able to read from Replica on preferred Rack identified in client.**
- This saves on Network Access Costs on Cloud e.g. AWS, for Read-Heavy workloads.  
➔ SIGNIFICANT COST SAVINGS.
- 2) In SC Mode, **client should be able to read from Replica when Master is down.**
- This prevents unwanted Timeouts on Reads when Master goes down.
  - Overall Client / Server discovery typically takes ~1.8 seconds to promote Replica to Master.

# What is the trade-off?

- Relaxed Reads from Replica come at the expense of session consistency guarantee.
- There will be corner cases, *though probability is quite low*, where **even for same session, stale reads** may be returned.
  - i.e. c1w2 could be returned instead of c1w3.
- Still, no dirty reads.** (i.e. uncommitted writes are not returned.)
- Customers demanding relaxed consistency reads are OK with these trade-offs in their data model.

## Session Consistency



# New Read Policy Options in SC Mode

**Ver 4.5.2.1+**, in SC Mode, introduces 4 distinct read policies.

Java Client Example: [ReadModeSC](#) settings:

- **LINEARIZE** - most strict, implements Global Read Linearizability, reads from Master.
- **SESSION** – *default*, implements session consistency, reads from Master.
- **ALLOW\_REPLICA** – allows reads from Master or any full (non-migrating) Replica. Session Consistency is not guaranteed.
- **ALLOW\_UNAVAILABLE** – "ALLOW\_REPLICA" reads even from UNAVAILABLE partitions.

# Client Behavior (Updated for Server version 4.5.2.1+)

Which node does the client read from?

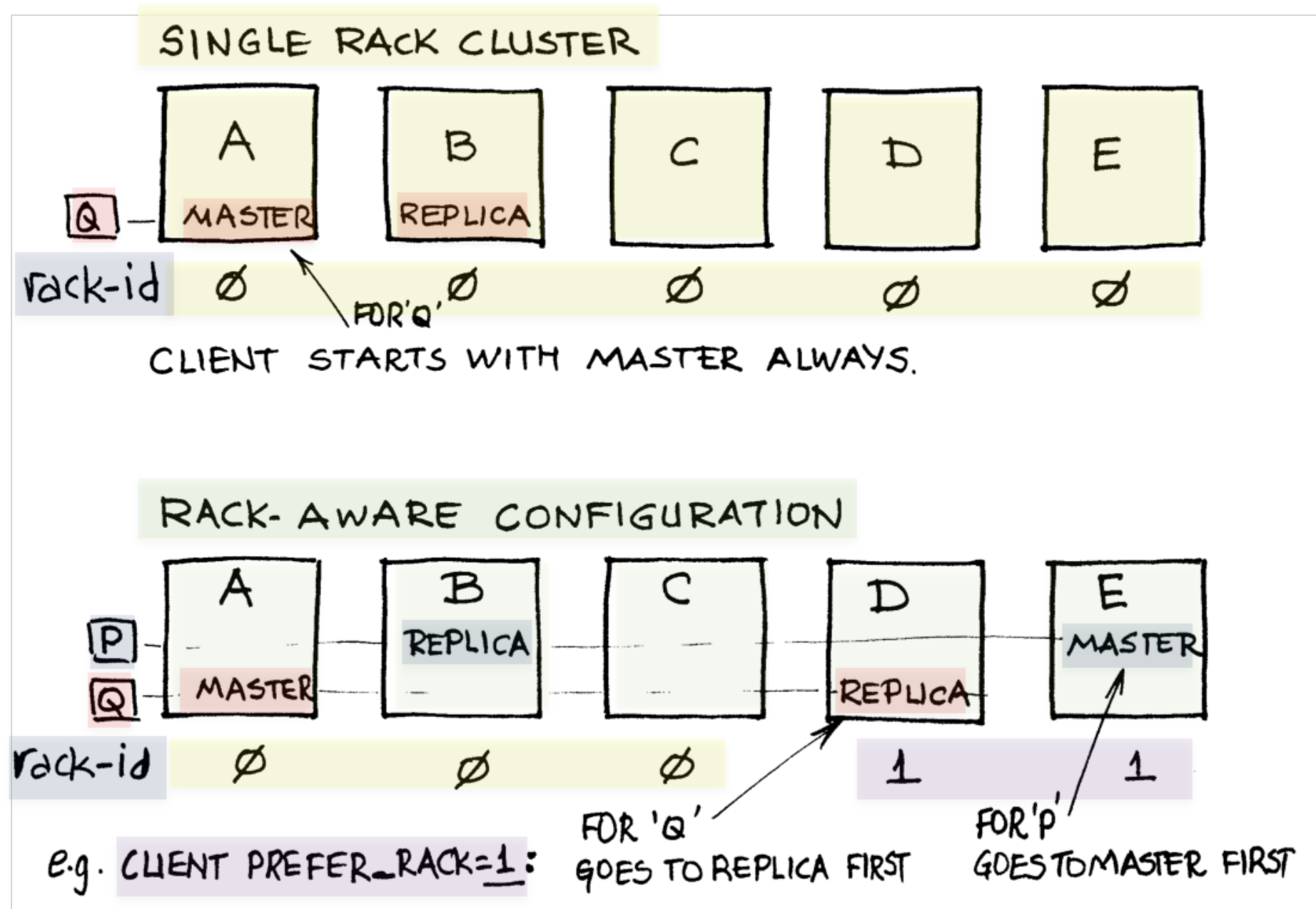
- LINEARIZE
- SESSION

From Master only.

- ALLOW\_REPLICA
- ALLOW\_UNAVAILABLE.

**Single Rack:** Master, if fails, then Replica.

**Rack-Aware w/Preferred rack Reads:** Master or Replica on preferred rack, if fails, Replica or Master on other rack.



# SC Mode Performance Comparison

- Comparable reads/writes in session consistency, global linearizability and AP mode.
- In steady cluster state, performance in SC and AP modes is comparable.

	SC Mode Global Linearizability	SC Mode Session Consistency	AP Mode
Update Latency	630 $\mu$ s	640 $\mu$ s	640 $\mu$ s
Read Latency	548 $\mu$ s	225 $\mu$ s	220 $\mu$ s
OPS	1.87 million	5.95 million	6 million

- 500M records, 8 byte objects, in-memory with persistence, RF=2.

# SC Mode Configuration Recommendations

Preferred SC Mode configuration options are:

- **Replication Factor = 2**
- Suggested **cluster size:  $\geq (2 \times RF) - 1$** .
  - Allows up to (Replication Factor – 1) failures.
- **Storage engine device preferred.** (commit-to-device ensures durability)
- **Zero Default TTL preferred.** (SC mode records should not need expiration or eviction.)



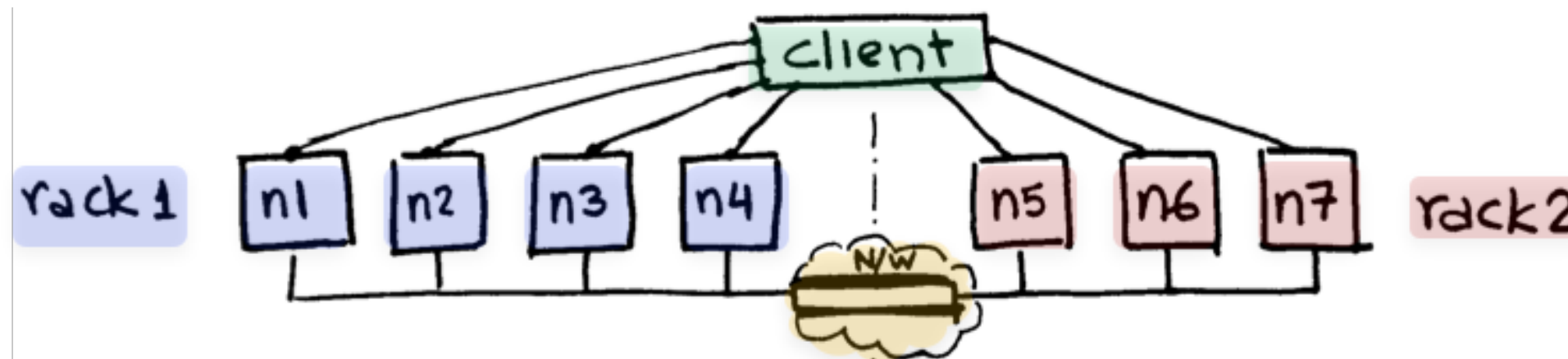
# Rack-Awareness (EE only) in SC Mode

**Rack Awareness:** Nodes from different racks are assigned to a partition.

- In SC namespace configuration on each node, assign node's rack-id.
- Different SC namespaces, in the same cluster, can specify different rack-id's  
→ rack awareness is on a namespace basis.
- By default, we have a single rack (default rack-id = 0) and the initial partition map does not need any adjustment (unless using Uniform Balance).

# Rack-Awareness in SC Mode – Commonly Used Pattern

- RF=2, # racks = 2, **odd number of nodes**



- If rack with minority nodes fails, we will have full availability on the majority rack.
- If rack with majority nodes fails, all availability will be lost.
  - **Rule:** Minority cluster needs both roster-master & roster-replica (full/subset combos)

# Q&A?

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